

The notion of crossing task for the cumulative scheduling problem and how to use it to compute lower bounds of the optimal makespan

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1 Abstract

In the Cumulative Scheduling Problem (CuSP) [2, 3, 4, 5], the aim is to schedule without preemption a set I of n independent tasks on a single resource composed of m identical machines. With each task i are associated a release date r_i , a processing time p_i , a tail q_i , and a resource consumption c_i , *i.e.* task i requires simultaneously c_i machines during its processing. The aim is to find a schedule minimizing the makespan C_{max} . Denoting by C_i the completion time of task i in such a schedule, we have : $C_{max} = \max_{i \in I} \{C_i + q_i\}$. We will present our results for the m machines problem for which all the c_i are equal to 1 and we generalize them on the CuSP.

Being given a trial value of C_{max} , a deadline $d_i = C_{max} - q_i$ can be associated with each task i . The question is then to know if there exists a feasible schedule satisfying the deadlines.

Définition 1 *Given a makespan C_{max} , a task i is called a punctual crossing task if and only if there exists an interval of time in which task i is necessarily scheduled, *i.e.* if there exists t such that $d_i - p_i \leq t < r_i + p_i$. If task i is necessarily scheduled during interval $[t - 1, t]$, we say that i is a t -punctual crossing task ($t \in \{1, \dots, C_{max}\}$).*

Proposition 1 *Given a makespan C_{max} , for each punctual crossing task i we have $r_i + 2p_i + q_i > C_{max}$.*

From this proposition, we can deduce that if $\max_{i \in I} \{r_i + 2p_i + q_i\} \leq C_{max}$, then there is no punctual crossing task. In the sequel, we denote by C_{max}^* the makespan associated with an optimal non-preemptive schedule.

An immediate consequence is that if there are strictly more than m t -punctual crossing tasks, then no non-preemptive schedule with a makespan less than or equal to C_{max}^* exists.

This result allows an alternative lower bound LB_1 for the CuSP associated with a non-preemptive schedule to be proposed. It can be computed in $O(n \log n)$. The approach aims to adjust C_{max} by computing the actual punctual crossing tasks and performing its increasing whenever this number exceeds m .

The following theorem can be stated :

Theorem 1.1 *If $C_{max}^* > \max_{i \in I} \{r_i + 2p_i + q_i\}$ then I contains at least $2m$ tasks and there is no punctual crossing task. Moreover, the quantity*

$$LB_2 = \min_{\substack{K=\{k_1, \dots, k_m\} \subset I, \\ J=\{j_1, \dots, j_m\} \subset I, \\ K \cap J = \emptyset}} \left\{ \frac{1}{m} (r_{k_1} + \dots + r_{k_m}) + \frac{1}{m} \sum_{i \in I} p_i + \frac{1}{m} (q_{j_1} + \dots + q_{j_m}) \right\}$$

is a lower bound of the makespan.

Next we come back to the general case when there is no assumption on C_{max}^* and we generalize the previous theorem. Finally we show its connection with energetic reasoning [1, 6].

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